

Knowledge Graph Representation Learning and NLP Applications

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Outline

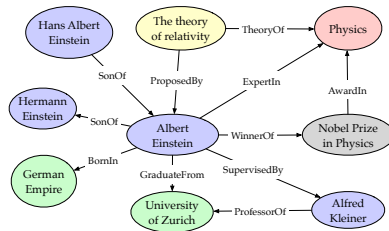
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Introduction

A knowledge graph is a structured representation of facts, consisting of entities, relationships, and semantic descriptions.

- (Albert Einstein, **BornIn**, German Empire)
- (Albert Einstein, **SonOf**, Hermann Einstein)
- (Albert Einstein, **GraduateFrom**, University of Zurich)
- (Albert Einstein, **WinnerOf**, Nobel Prize in Physics)
- (Albert Einstein, **ExpertIn**, Physics)
- (Nobel Prize in Physics, **AwardIn**, Physics)
- (The theory of relativity, **TheoryOf**, Physics)
- (Albert Einstein, **SupervisedBy**, Alfred Kleiner)
- (Alfred Kleiner, **ProfessorOf**, University of Zurich)
- (The theory of relativity, **ProposedBy**, Albert Einstein)
- (Hans Albert Einstein, **SonOf**, Albert Einstein)

(a) Factual triples in knowledge base.



(b) Entities and relations in knowledge graph.

Figure: An example of knowledge base and knowledge graph.

(Ji et al., 2022)

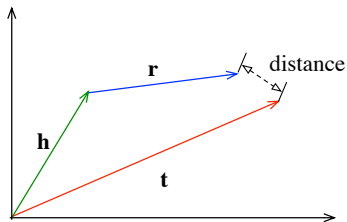
Why Knowledge Graphs?

- Context:
 - entities (real-world objects and abstract concepts)
 - relation between entities, types, and properties
- Relational Reasoning
- Intrinsic Explainability
- Others: efficient search, flexibility ...

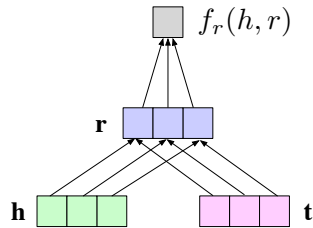
This presentation:

- How to represent and encode factual knowledge triples
- Knowledge graphs applied to NLP and healthcare tasks.

How to Learn Knowledge Graph Representation



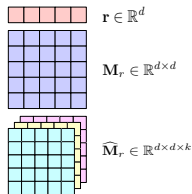
(a) Translational distance-based scoring of TransE.



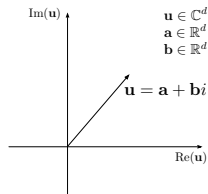
(b) Semantic similarity-based scoring of DistMult.

Figure: Illustrations of distance-based and similarity matching based scoring functions taking TransE (Bordes et al., 2013) and DistMult (Yang et al., 2015) as examples.

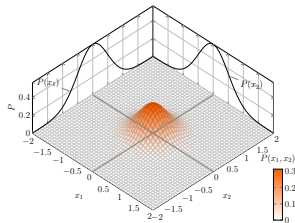
Representation Space



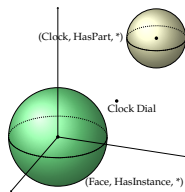
(a) Point-wise space.



(b) Complex vector space.



(c) Gaussian distribution.



(d) Manifold space.

- Point-Wise Space: widely applied
- Complex Space: real and imaginary parts
- Gaussian distribution: (un)certainities of entities and relations
- Manifold Space: a set of points with neighborhoods by the set theory

Encoding Models

encode the interactions of entities and relations through specific model architectures,

- linear/bilinear models: relations as a linear/bilinear mapping by projecting head entities into a representation space close to tail entities
- factorization models: decompose relational data into low-rank matrices for representation learning
- neural networks: encode relational data with non-linear neural activation and more complex network structures by matching semantic similarity of entities and relations

Linear/Bilinear and Factorization Models

Linear scoring function

$$g_r(h, t) = M_r^T \begin{pmatrix} h \\ t \end{pmatrix} \quad (1)$$

Bilinear scoring function

$$f_r(h, t) = h^T M_r t \quad (2)$$

Factorization

RESCAL (Nickel et al., 2011)

three-way rank- r factorization RESCAL over each relational slice of knowledge graph tensor.

$$\mathcal{X}_k \approx AR_kA^T \quad (3)$$

Neural Networks

MLP

$$f_r(h, t) = \sigma(w^T \sigma(W[h, r, t])), \quad (4)$$

NTN (Socher et al., 2013)

$$f_r(h, t) = r^T \sigma(h^T \hat{M}t + M_{r,1}h + M_{r,2}t + b_r), \quad (5)$$

CNN input triples into dense layer and convolution operation to learn semantic representation

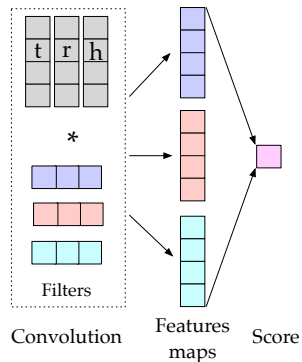


Figure: CNN (Nguyen et al., 2018)

Neural Networks

GCN (Shang et al., 2019) acts as encoder of knowledge graphs to produce entity and relation embeddings.

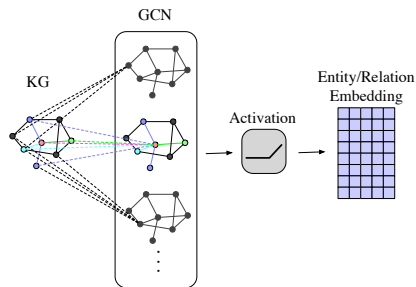


Figure: GCN (Shang et al., 2019)

RNN

RSN encodes entity-relation sequences and skips relations discriminatively.

$$h'_t = \begin{cases} h_t & x_t \in \mathcal{E} \\ S_1 h_t + S_2 x_{t-1} & x_t \in \mathcal{R} \end{cases} \quad (6)$$

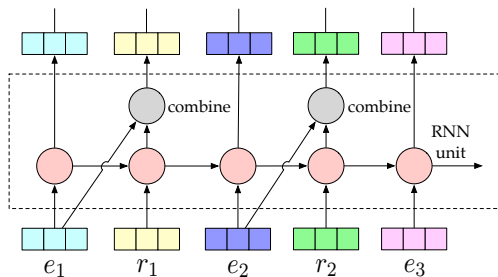


Figure: RSN (Guo et al., 2019)

Transformers

Transformer-based CoKE (Wang et al., 2019) encodes triples as sequences with an entity replaced by [MASK].

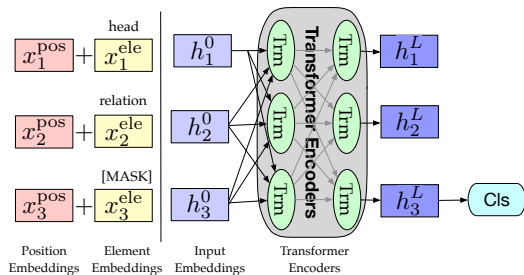


Figure: CoKE (Wang et al., 2019)

Incorporate Knowledge Graphs for NLP

Three paradigms:

- Incorporate large-scale knowledge graph in pretraining (in Sec. 2)
- Inject knowledge into model architecture [e.g., SentiLSTM (Ma et al., 2018)]
- Infuse knowledge-aware representations into text features [e.g., CompareNet (Hu et al., 2021)]

Knowledge-aware Language Models

- The success gained by pretraining self-supervised language models
- Integrating factual knowledge into language representation via pretraining

Knowledge-aware Language Models

Discriminating informative entities

- ERNIE-Tsinghua (Zhang et al., 2019): entity & random masking
- ERNIE-Baidu (Sun et al., 2019): entity and phrase masking
- GLM (Shen et al., 2020): graph-guided (linking) entity masking

Subgraph extraction

- BERT-MK (He et al., 2020): knowledge subgraph (multi-head attention)
- CoLAKE (Sun et al., 2020): word graph & knowledge subgraph (concat)

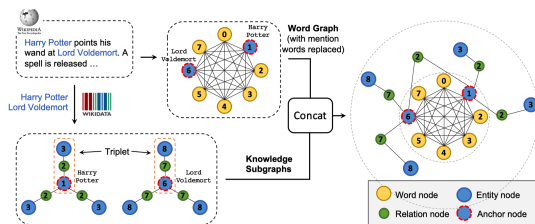
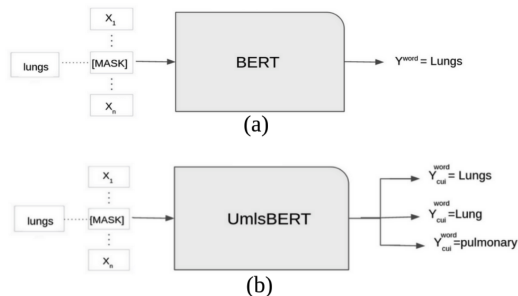


Figure: CoLAKE (Sun et al., 2020)

Knowledge-aware Language Models

Multi-label Concept (Synonym) Modeling

- UmlsBERT (Michalopoulos et al., 2021): concepts in UMLS Metathesaurus



Joint Training

- KEPLER (Wang et al., 2020): knowledge embedding + MLM losses

NLP Applications: Sentiment Analysis

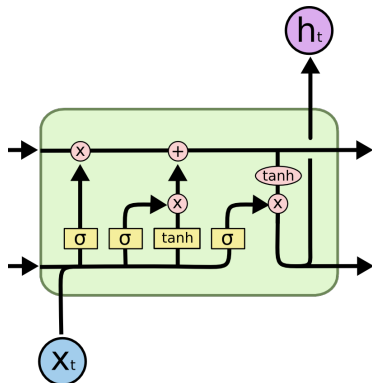


Figure: LSTM (Source: C. Olah)

Sentic LSTM (Ma et al., 2018)

$$f_i = \sigma(W_f[x_i, h_{i-1}, \mu_i] + b_f)$$

$$I_i = \sigma(W_I[x_i, h_{i-1}, \mu_i] + b_I)$$

$$\tilde{C}_i = \tanh(W_C[x_i, h_{i-1}] + b_C)$$

$$C_i = f_i * C_{i-1} + I_i * \tilde{C}_i$$

$$o_i = \sigma(W_o[x_i, h_{i-1}, \mu_i] + b_o)$$

$$o_i^c = \sigma(W_{co}[x_i, h_{i-1}, \mu_i] + b_{co})$$

$$h_i = o_i * \tanh(C_i) + o_i^c * \tanh(W_c \mu_i)$$

μ_i : knowledge concepts

NLP Applications: Fake News Detection

Gating

$$e_{KB} = g_e \odot e_s + (1 - g_e) \odot e_d$$

Entity Comparison

$$a_i = f_{cmp}(e_c, W_e \cdot e_{KB})$$

$$f_{cmp}(x, y) = W_a[x - y, x \odot y]$$

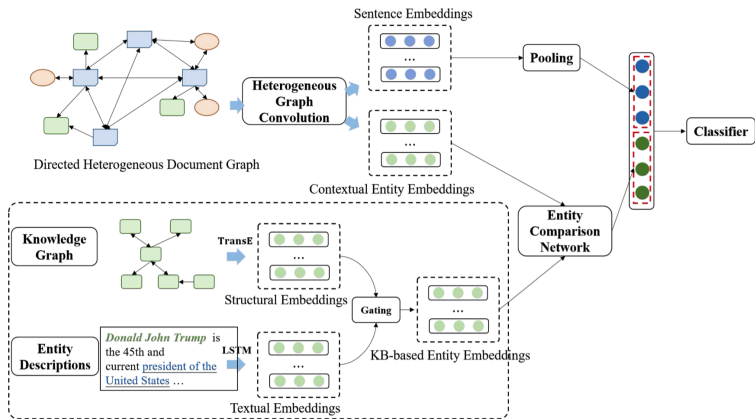


Figure: CompareNet (Hu et al., 2021)

NLP Applications: Healthcare

Medical NLI (Sharma et al., 2019)

$$e_w = e_{\text{BioELMo},w} \oplus e_{\text{DistMult},w} \oplus e_{\text{Senti}_w}$$

Medical Code Prediction

- Code-wise attention
 $\alpha_i = \text{softmax}(H^T v_i)$
- Aggregation:
 $U = \lambda W_s S + D^T W_d$

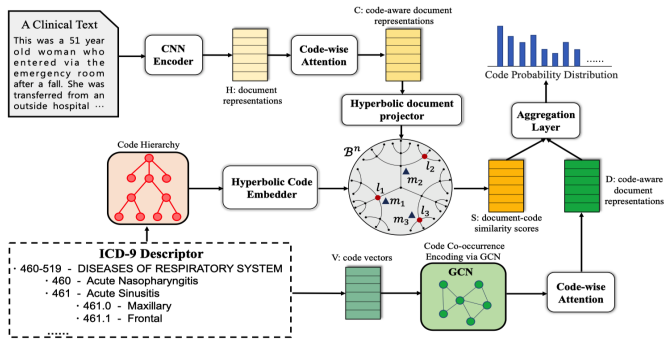


Figure: HyperCore (Cao et al., 2020)

Summary

Today's presentation:

- Knowledge Graph Representation Learning (three aspects)
- Knowledge-aware NLP Applications (three paradigms)

More applications of KGs:

- Ontology-guided distant supervision
- Healthcare: drug-drug interaction and drug adverse event detection
- And more, e.g., question answering and recommendation systems

Open Questions:

- Construction of knowledge graphs (manual v.s. automatic)
- Knowledge graph database indexing and query
- Dynamic knowledge graphs

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